

**Questions for state exams in the subject: Design of mechatronic systems**  
**Study program: Industrial mechatronics**

**AR: 2020/2021**

1. Example of Application of a Modern Control System, Basic Operations of Block Algebra and Possibilities of Block Diagram Editing.
2. Stability of the system and Types of Stability Criteria.
3. Nyquist Polar Plot of Second Order System  $G(s) = \frac{1}{(1 + sT_1)(1 + sT_2)}$
4. The Nyquist Stability Criterion.
5. The Rouths Stability Criterion.
6. Gain and Phase Margin in the Bode Diagram.
7. PID Control.
8. Ziegler and Nichols Control Method.
9. Local Coordination Frame, Global Coordination Frame, Rotation about Global Cartesian Axes, Euler angles.
10. Rigid Body Motion
11. Homogenous Transformation
12. Forward Kinematics and Denavit – Hartenberg Notation
13. Inverse Kinematics of an Articulated Robot.
14. Forward Velocity Kinematics.
15. Jacobian Matrix for an Articulated Robot.

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